BMP180
Digital pressure sensor

Bosch Sensortec

BMP180 Data sheet

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Notes Data in this document are subject to change without notice. Product photos and pictures are for illustration purposes only and may differ from the real product's appearance.
BMP180

DIGITAL PRESSURE SENSOR

Key features

Pressure range: 300 ... 1100hPa (+9000m ... -500m relating to sea level)
Supply voltage: 1.8 ... 3.6V ($V_{DD}$)
                        1.62V ... 3.6V ($V_{DDIO}$)
Package: LGA package with metal lid
Small footprint: 3.6mm x 3.8mm
Super-flat: 0.93mm height
Low power: 5µA at 1 sample / sec. in standard mode
Low noise: 0.06hPa (0.5m) in ultra low power mode
                        0.02hPa (0.17m) advanced resolution mode

- Temperature measurement included
- I²C interface
- Fully calibrated
- Pb-free, halogen-free and RoHS compliant,
- MSL 1

Typical applications

- Enhancement of GPS navigation (dead reckoning, slope detection, etc.)
- In- and out-door navigation
- Leisure and sports
- Weather forecast
- Vertical velocity indication (rise/sink speed)
BMP180 general description

The BMP180 is the function compatible successor of the BMP085, a new generation of high precision digital pressure sensors for consumer applications.

The ultra-low power, low voltage electronics of the BMP180 is optimized for use in mobile phones, PDAs, GPS navigation devices and outdoor equipment. With a low altitude noise of merely 0.25m at fast conversion time, the BMP180 offers superior performance. The I²C interface allows for easy system integration with a microcontroller.

The BMP180 is based on piezo-resistive technology for EMC robustness, high accuracy and linearity as well as long term stability.

Robert Bosch is the world market leader for pressure sensors in automotive applications. Based on the experience of over 400 million pressure sensors in the field, the BMP180 continues a new generation of micro-machined pressure sensors.
Index of Contents

1. ELECTRICAL CHARACTERISTICS ................................................................. 6
2. ABSOLUTE MAXIMUM RATINGS ................................................................. 8
3. OPERATION .................................................................................................. 9
   3.1 GENERAL DESCRIPTION ...................................................................... 9
   3.2 GENERAL FUNCTION AND APPLICATION SCHEMATICS ......................... 9
   3.3 MEASUREMENT OF PRESSURE AND TEMPERATURE ......................... 11
       3.3.1 Hardware pressure sampling accuracy modes .............................. 12
       3.3.2 Software pressure sampling accuracy modes .............................. 13
   3.4 CALIBRATION COEFFICIENTS ............................................................... 13
   3.5 CALCULATING PRESSURE AND TEMPERATURE ................................. 14
   3.6 CALCULATING ABSOLUTE ALTITUDE .................................................. 16
   3.7 CALCULATING PRESSURE AT SEA LEVEL .............................................. 17
4. GLOBAL MEMORY MAP .................................................................................. 18
5. \^ I^2C INTERFACE ............................................................................................ 19
   5.1 \^ I^2C SPECIFICATION ....................................................................... 19
   5.2 DEVICE AND REGISTER ADDRESS ...................................................... 20
   5.3 \^ I^2C PROTOCOL ............................................................................... 20
   5.4 START TEMPERATURE AND PRESSURE MEASUREMENT ..................... 21
   5.5 READ A/D CONVERSION RESULT OR E^2PROM DATA ....................... 22
6. PACKAGE ......................................................................................................... 23
   6.1 PIN CONFIGURATION .......................................................................... 23
   6.2 OUTLINE DIMENSIONS ......................................................................... 24
       6.2.1 Bottom view ............................................................................... 24
       6.2.2 Top view .................................................................................... 25
       6.2.3 Side view .................................................................................... 25
   6.3 MOISTURE SENSITIVITY LEVEL AND SOLDERING ................................. 26
   6.4 ROHS COMPLIANCE ............................................................................. 26
   6.5 MOUNTING AND ASSEMBLY RECOMMENDATIONS .............................. 26
7. LEGAL DISCLAIMER ......................................................................................... 27
7.1 ENGINEERING SAMPLES ........................................................................................................27
7.2 PRODUCT USE ......................................................................................................................27
7.3 APPLICATION EXAMPLES AND HINTS ...............................................................................27

8. DOCUMENT HISTORY AND MODIFICATION ......................................................................28
1. Electrical characteristics

If not stated otherwise, the given values are ±3-Sigma values over temperature/voltage range in the given operation mode. All values represent the new part specification; additional solder drift is shown separately.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Condition</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating temperature</td>
<td>( T_A )</td>
<td>operational</td>
<td>(-40)</td>
<td>(+85)</td>
<td></td>
<td>( ^\circ C )</td>
</tr>
<tr>
<td></td>
<td></td>
<td>full accuracy</td>
<td>(0)</td>
<td>(+65)</td>
<td></td>
<td>( ^\circ C )</td>
</tr>
<tr>
<td>Supply voltage</td>
<td>( V_{DD} )</td>
<td>ripple max. 50mVpp</td>
<td>(1.8)</td>
<td>(2.5)</td>
<td>(3.6)</td>
<td>( V )</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>(1.62)</td>
<td>(2.5)</td>
<td>(3.6)</td>
<td>( V )</td>
</tr>
<tr>
<td>Supply current @ 1 sample / sec. 25°C</td>
<td></td>
<td>ultra low power mode</td>
<td>(3)</td>
<td></td>
<td></td>
<td>( \mu A )</td>
</tr>
<tr>
<td></td>
<td>( I_{DDLOW} )</td>
<td>standard mode</td>
<td>(5)</td>
<td></td>
<td></td>
<td>( \mu A )</td>
</tr>
<tr>
<td></td>
<td>( I_{DDSTD} )</td>
<td>high resolution mode</td>
<td>(7)</td>
<td></td>
<td></td>
<td>( \mu A )</td>
</tr>
<tr>
<td></td>
<td>( I_{DDHR} )</td>
<td>Ultra high res. mode</td>
<td>(12)</td>
<td></td>
<td></td>
<td>( \mu A )</td>
</tr>
<tr>
<td></td>
<td>( I_{DDUHR} )</td>
<td>Advanced res. mode</td>
<td>(32)</td>
<td></td>
<td></td>
<td>( \mu A )</td>
</tr>
<tr>
<td>Peak current</td>
<td>( I_{peak} )</td>
<td>during conversion</td>
<td>(650)</td>
<td>(1000)</td>
<td></td>
<td>( \mu A )</td>
</tr>
<tr>
<td>Standby current</td>
<td>( I_{DDSBM} )</td>
<td>@ 25°C</td>
<td>(0.1)</td>
<td>(4)</td>
<td></td>
<td>( \mu A )</td>
</tr>
<tr>
<td>Relative accuracy pressure</td>
<td></td>
<td>( V_{DD} = 3.3V )</td>
<td>(950\ldots1050) hPa ( @ 25 ^\circ C )</td>
<td>(\pm0.12)</td>
<td>( hPa )</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>(700\ldots900) hPa ( 25 \ldots 40 ^\circ C )</td>
<td>(\pm0.12)</td>
<td>( hPa )</td>
<td></td>
</tr>
<tr>
<td>Absolute accuracy pressure</td>
<td></td>
<td>( V_{DD} = 3.3V )</td>
<td>(300\ldots1100) hPa ( 0 \ldots +65 ^\circ C )</td>
<td>(-4.0)</td>
<td>(\pm1.0)</td>
<td>( hPa )</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>(300\ldots1100) hPa ( -20 \ldots 0 ^\circ C )</td>
<td>(-6.0)</td>
<td>(\pm1.0)</td>
<td>( hPa )</td>
</tr>
<tr>
<td>Resolution of output data</td>
<td></td>
<td>pressure</td>
<td>(0.01)</td>
<td></td>
<td></td>
<td>( hPa )</td>
</tr>
<tr>
<td></td>
<td></td>
<td>temperature</td>
<td>(0.1)</td>
<td></td>
<td></td>
<td>( ^\circ C )</td>
</tr>
<tr>
<td>Noise in pressure</td>
<td></td>
<td>see table on page 12-13</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Absolute accuracy temperature</td>
<td></td>
<td>( V_{DD} = 3.3V )</td>
<td>( @ 25 ^\circ C )</td>
<td>(-1.5)</td>
<td>(\pm0.5)</td>
<td>( +1.5 )</td>
</tr>
<tr>
<td></td>
<td></td>
<td>( 0 \ldots +65 ^\circ C )</td>
<td>(-2.0)</td>
<td>(\pm1.0)</td>
<td>( +2.0 )</td>
<td>( ^\circ C )</td>
</tr>
</tbody>
</table>

\(^1\) at 85°C
<table>
<thead>
<tr>
<th>Conversion time pressure</th>
<th>tc_p_low</th>
<th>ultra low power mode</th>
<th>3</th>
<th>4.5</th>
<th>ms</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>tc_p_std</td>
<td>standard mode</td>
<td>5</td>
<td>7.5</td>
<td>ms</td>
</tr>
<tr>
<td></td>
<td>tc_p_hr</td>
<td>high resolution mode</td>
<td>9</td>
<td>13.5</td>
<td>ms</td>
</tr>
<tr>
<td></td>
<td>tc_p_luhr</td>
<td>ultra high res. mode</td>
<td>17</td>
<td>25.5</td>
<td>ms</td>
</tr>
<tr>
<td></td>
<td>tc_p_ar</td>
<td>Advanced res. mode</td>
<td>51</td>
<td>76.5</td>
<td>ms</td>
</tr>
<tr>
<td>Conversion time temperature</td>
<td>tc_temp</td>
<td>standard mode</td>
<td>3</td>
<td>4.5</td>
<td>ms</td>
</tr>
<tr>
<td>Serial data clock</td>
<td>f_SCL</td>
<td></td>
<td></td>
<td>3.4</td>
<td>MHz</td>
</tr>
<tr>
<td>Solder drifts</td>
<td></td>
<td>Minimum solder height 50µm</td>
<td>-0.5</td>
<td>+2</td>
<td>hPa</td>
</tr>
<tr>
<td>Long term stability**</td>
<td></td>
<td>12 months</td>
<td></td>
<td>±1.0</td>
<td>hPa</td>
</tr>
</tbody>
</table>

* The typical value is: -1±1
** Long term stability is specified in the full accuracy operating pressure range 0 ... 65°C
2. Absolute maximum ratings

Table 2: Absolute maximum ratings

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Condition</th>
<th>Min</th>
<th>Max</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Storage temperature</td>
<td></td>
<td>-40</td>
<td>+85</td>
<td>°C</td>
</tr>
<tr>
<td>Supply voltage</td>
<td>all pins</td>
<td>-0.3</td>
<td>+4.25</td>
<td>V</td>
</tr>
<tr>
<td>ESD rating</td>
<td>HBM, R = 1.5kΩ, C = 100pF</td>
<td>±2</td>
<td></td>
<td>kV</td>
</tr>
<tr>
<td>Overpressure</td>
<td></td>
<td>10,000</td>
<td></td>
<td>hPa</td>
</tr>
</tbody>
</table>

The BMP180 has to be handled as Electrostatic Sensitive Device (ESD).

Figure 1: ESD
3. Operation

3.1 General description

The BMP180 is designed to be connected directly to a microcontroller of a mobile device via the I2C bus. The pressure and temperature data has to be compensated by the calibration data of the E²PROM of the BMP180.

3.2 General function and application schematics

The BMP180 consists of a piezo-resistive sensor, an analog to digital converter and a control unit with E²PROM and a serial I²C interface. The BMP180 delivers the uncompensated value of pressure and temperature. The E²PROM has stored 176 bit of individual calibration data. This is used to compensate offset, temperature dependence and other parameters of the sensor.

- UP = pressure data (16 to 19 bit)
- UT = temperature data (16 bit)
Figure 2: Typical application circuit

Note:
(1) Pull-up resistors for I²C bus, $R_p = 2.2k\Omega \ldots 10k\Omega$, typ. 4.7kΩ
3.3 Measurement of pressure and temperature

For all calculations presented here an ANSI C code is available from Bosch Sensortec (“BMP180 _API”).

The microcontroller sends a start sequence to start a pressure or temperature measurement. After converting time, the result value (UP or UT, respectively) can be read via the I²C interface. For calculating temperature in °C and pressure in hPa, the calibration data has to be used. These constants can be read out from the BMP180 E²PROM via the I²C interface at software initialization.

The sampling rate can be increased up to 128 samples per second (standard mode) for dynamic measurement. In this case, it is sufficient to measure the temperature only once per second and to use this value for all pressure measurements during the same period.

Figure 3: Measurement flow BMP180
3.3.1 Hardware pressure sampling accuracy modes
By using different modes the optimum compromise between power consumption, speed and resolution can be selected, see below table.

Table 3: Overview of BMP180 hardware accuracy modes, selected by driver software via the variable oversampling_setting

<table>
<thead>
<tr>
<th>Mode</th>
<th>Parameter oversampling_setting</th>
<th>Internal number of samples</th>
<th>Conversion time pressure max. [ms]</th>
<th>Avg. current @ 1 sample/s typ. [µA]</th>
<th>RMS noise typ. [hPa]</th>
<th>RMS noise typ. [m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>ultra low power</td>
<td>0</td>
<td>1</td>
<td>4.5</td>
<td>3</td>
<td>0.06</td>
<td>0.5</td>
</tr>
<tr>
<td>standard</td>
<td>1</td>
<td>2</td>
<td>7.5</td>
<td>5</td>
<td>0.05</td>
<td>0.4</td>
</tr>
<tr>
<td>high resolution</td>
<td>2</td>
<td>4</td>
<td>13.5</td>
<td>7</td>
<td>0.04</td>
<td>0.3</td>
</tr>
<tr>
<td>ultra high resolution</td>
<td>3</td>
<td>8</td>
<td>25.5</td>
<td>12</td>
<td>0.03</td>
<td>0.25</td>
</tr>
</tbody>
</table>

For further information on noise characteristics see the relevant application note “Noise in pressure sensor applications”.

All modes can be performed at higher speeds, e.g. up to 128 times per second for standard mode, with the current consumption increasing proportionally to the sample rate.
3.3.2 Software pressure sampling accuracy modes

For applications where a low noise level is critical, averaging is recommended if the lower bandwidth is acceptable. Oversampling can be enabled using the software API driver (with OSR = 3).

Table 4: Overview of BMP180 software accuracy mode, selected by driver software via the variable `software_oversampling_setting`

<table>
<thead>
<tr>
<th>Mode</th>
<th>Parameter</th>
<th>software_oversampling_setting</th>
<th>Conversion time pressure max. [ms]</th>
<th>Avg. current @ 1 sample/s typ. [µA]</th>
<th>RMS noise typ. [hPa]</th>
<th>RMS noise typ. [m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Advanced resolution</td>
<td>3</td>
<td>1</td>
<td>76.5</td>
<td>32</td>
<td>0.02</td>
<td>0.17</td>
</tr>
</tbody>
</table>

3.4 Calibration coefficients

The 176 bit E²PROM is partitioned in 11 words of 16 bit each. These contain 11 calibration coefficients. Every sensor module has individual coefficients. Before the first calculation of temperature and pressure, the master reads out the E²PROM data. The data communication can be checked by checking that none of the words has the value 0 or 0xFFFF.

Table 5: Calibration coefficients

<table>
<thead>
<tr>
<th>Parameter</th>
<th>BMP180 reg adr</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>MSB</td>
</tr>
<tr>
<td>AC1</td>
<td>0xAA</td>
</tr>
<tr>
<td>AC2</td>
<td>0xAC</td>
</tr>
<tr>
<td>AC3</td>
<td>0xAE</td>
</tr>
<tr>
<td>AC4</td>
<td>0xB0</td>
</tr>
<tr>
<td>AC5</td>
<td>0xB2</td>
</tr>
<tr>
<td>AC6</td>
<td>0xB4</td>
</tr>
<tr>
<td>B1</td>
<td>0xB6</td>
</tr>
<tr>
<td>B2</td>
<td>0xB8</td>
</tr>
<tr>
<td>MB</td>
<td>0xBA</td>
</tr>
<tr>
<td>MC</td>
<td>0xBC</td>
</tr>
<tr>
<td>MD</td>
<td>0xBE</td>
</tr>
</tbody>
</table>
3.5 Calculating pressure and temperature

The mode (ultra low power, standard, high, ultra high resolution) can be selected by the variable `oversampling_setting` (0, 1, 2, 3) in the C code.

Calculation of true temperature and pressure in steps of 1Pa (= 0.01hPa = 0.01mbar) and temperature in steps of 0.1°C.

The following figure shows the detailed algorithm for pressure and temperature measurement.

This algorithm is available to customers as reference C source code ("BMP180_API") from Bosch Sensortec and via its sales and distribution partners. Please contact your Bosch Sensortec representative for details.
Calculation of pressure and temperature for BMP180

Start

Read calibration data from the EEPROM of the BMP180
- AC1 (0x1A, 0x2B) (16 bit)
- AC2 (0x1C, 0x2C) (16 bit)
- AC3 (0x1E, 0x2D) (16 bit)
- AC4 (0x8B, 0x2E) (16 bit)
- AC5 (0x23, 0x3B) (16 bit)
- AC6 (0x4B, 0x3C) (16 bit)
- B1 (0x66, 0x47) (16 bit)
- B2 (0x68, 0x38) (16 bit)
- MB (0x39, 0x46) (16 bit)
- MC (0x3C, 0x4B) (16 bit)
- MD (0x4E, 0x5B) (16 bit)

Read uncompensated temperature value
- write 0x2E into reg 0xF4, wait 4.5ms
- read reg 0xF6 (MSB), 0xF7 (LSB)

UT = MSB << 8 + LSB

Read uncompensated pressure value
- write 0x0A into reg 0xF4, wait 4.5ms
- read reg 0xF5 (MSB), 0xF6 (LSB), 0xF7 (XLSB)

UP = (MSB<<16 + LSB<<8 + XLSB) >> 8 (ones)

Calculate true temperature
- \( X_1 = (UT - AC6) \times AC1 + AC5 \times 2^{-16} \)
- \( X_2 = X_1 + MC \times 2^{-8} \)
- \( B_5 = X_1 + X_2 \)
- \( T = (X_5 + X_1 + X_2 + 1) \times 2^{-4} \)

Calculate true pressure
- \( B_6 = B_5 \times 2^{14} \)
- \( X_1 = (B_6 \times B_5 + B_6^{2} + 2) \times 2^{-11} \)
- \( X_2 = X_1 + X_2 \times 2^{-8} \)
- \( X_3 = (X_1 + X_2 + 2) \times 2^{-6} \)
- \( X_4 = (X_1 + X_2 + 2) \times 2^{-12} \)
- \( X_5 = (X_1 + X_2 + 2) \times 2^{-2} \)
- \( X_6 = (X_1 + X_2 + 2) \times 2^{-4} \)
- \( B_7 = (X_6 + 4776) \times 2^{-16} \)
- \( B_8 = \text{if } B_7 < 0 \times 2^{15} \)
- \( B_9 = \text{if } B_7 > 0 \times 2^{15} \)
- \( P = \text{if } B_9 < 0 \times 2^{15} \)
- \( P = \text{if } B_9 > 0 \times 2^{15} \)
- \( P = \text{if } B_9 < 0 \times 2^{15} \)
- \( P = \text{if } B_9 > 0 \times 2^{15} \)
- \( P = \text{if } B_9 < 0 \times 2^{15} \)
- \( P = \text{if } B_9 > 0 \times 2^{15} \)

Display temperature and pressure value

Example C code function:
- \( \text{bmp180_get_cal_param} \)
- \( \text{bmp180_get_ut} \)
- \( \text{bmp180_get_up} \)
- \( \text{bmp180_get_temperature} \)
- \( \text{bmp180_get_sp} \)

Figure 4: Algorithm for pressure and temperature measurement

Note: Specifications within this document are subject to change without notice.
3.6 Calculating absolute altitude

With the measured pressure $p$ and the pressure at sea level $p_0$ e.g. 1013.25hPa, the altitude in meters can be calculated with the international barometric formula:

$$ altitude = 44330 \times \left( 1 - \left( \frac{p}{p_0} \right)^{\frac{1}{5.255}} \right) $$

Thus, a pressure change of $\Delta p = 1$hPa corresponds to 8.43m at sea level.

![Diagram showing the relationship between barometric pressure and altitude](image-url)

Figure 5: Transfer function: Altitude over sea level – Barometric pressure
3.7 Calculating pressure at sea level

With the measured pressure $p$ and the absolute altitude the pressure at sea level can be calculated:

$$p_0 = \frac{p}{1 - \frac{\text{altitude}}{44330}}^{5.255}$$

Thus, a difference in altitude of $\Delta \text{altitude} = 10\text{m}$ corresponds to $1.2\text{hPa}$ pressure change at sea level.
4. Global Memory Map

The memory map below shows all externally accessible data registers which are needed to operate BMP180. The left columns show the memory addresses. The columns in the middle depict the content of each register bit. The colors of the bits indicate whether they are read-only, write-only or read- and writable. The memory is volatile so that the writable content has to be re-written after each power-on.

Not all register addresses are shown. These registers are reserved for further Bosch factory testing and trimming.

<table>
<thead>
<tr>
<th>Register Name</th>
<th>Register Address</th>
<th>bit7</th>
<th>bit6</th>
<th>bit5</th>
<th>bit4</th>
<th>bit3</th>
<th>bit2</th>
<th>bit1</th>
<th>bit0</th>
<th>Reset state</th>
</tr>
</thead>
<tbody>
<tr>
<td>out_xlsb</td>
<td>F8h</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>00h</td>
</tr>
<tr>
<td>out_lsb</td>
<td>F7h</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>adc_out_xlsb&lt;7:3&gt;</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>out_msb</td>
<td>F6h</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>adc_out_lsb&lt;7:0&gt;</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>ctrl_meas</td>
<td>F4h</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>oss&lt;1:0&gt;</td>
<td>sco</td>
<td>measurement control</td>
<td></td>
<td></td>
</tr>
<tr>
<td>soft reset</td>
<td>E0h</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>id</td>
<td>D0h</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>id&lt;7:0&gt;</td>
<td></td>
<td></td>
<td></td>
<td>05h</td>
</tr>
<tr>
<td>calib21 downto calib0</td>
<td>BFh downto AAh</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>calib21&lt;7:3&gt;</td>
<td>downto calib0&lt;7:0&gt;</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Figure 6: Memory map

**Measurement control (register F4h <4:0>):** Controls measurements. Refer to Figure 6 for usage details.

**Sco (register F4h <5>):** Start of conversion. The value of this bit stays “1” during conversion and is reset to “0” after conversion is complete (data registers are filled).

**Oss (register F4h <7:6>):** controls the oversampling ratio of the pressure measurement (00b: single, 01b: 2 times, 10b: 4 times, 11b: 8 times).

**Soft reset (register E0h):** Write only register. If set to 0xB6, will perform the same sequence as power on reset.

**Chip-id (register D0h):** This value is fixed to 0x55 and can be used to check whether communication is functioning.

After conversion, data registers can be read out in any sequence (i.e. MSB first or LSB first). Using a burst read is not mandatory.
5. I²C Interface

- I²C is a digital two wire interface
- Clock frequencies up to 3.4Mbit/sec. (I²C standard, fast and high-speed mode supported)
- SCL and SDA needs a pull-up resistor, typ. 4.7kOhm to VDDIO
  (one resistor each for all the I²C bus)

The I²C bus is used to control the sensor, to read calibration data from the E²PROM and to read the measurement data when A/D conversion is finished. SDA (serial data) and SCL (serial clock) have open-drain outputs.

For detailed I²C-bus specification please refer to:

5.1 I²C specification

Table 6: Electrical parameters for the I²C interface

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Min.</th>
<th>Typ</th>
<th>Max.</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Clock input frequency</td>
<td>fSCL</td>
<td></td>
<td></td>
<td>3.4</td>
<td>MHz</td>
</tr>
<tr>
<td>Input-low level</td>
<td>VIL</td>
<td>0</td>
<td></td>
<td>0.2 * VDDIO</td>
<td>V</td>
</tr>
<tr>
<td>Input-high level</td>
<td>VIH</td>
<td>0.8 * VDDIO</td>
<td></td>
<td>VDDIO</td>
<td>V</td>
</tr>
<tr>
<td>Voltage output low level @ VDDIO = 1.62V, IOL = 3mA</td>
<td>VDL</td>
<td></td>
<td></td>
<td>0.3</td>
<td>V</td>
</tr>
<tr>
<td>SDA and SCL pull-up resistor</td>
<td>Rpull-up</td>
<td>2.2</td>
<td></td>
<td>10</td>
<td>kOhm</td>
</tr>
<tr>
<td>SDA sink current @ VDDIO = 1.62V, VOL = 0.3V</td>
<td>ISDA_sink</td>
<td></td>
<td>9</td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td>Start-up time after power-up, before first communication</td>
<td>tStart</td>
<td>10</td>
<td></td>
<td></td>
<td>Ms</td>
</tr>
</tbody>
</table>
5.2 Device and register address

The BMP180 module address is shown below. The LSB of the device address distinguishes between read (1) and write (0) operation, corresponding to address 0xEF (read) and 0xEE (write).

<table>
<thead>
<tr>
<th>A7</th>
<th>A6</th>
<th>A5</th>
<th>A4</th>
<th>A3</th>
<th>A2</th>
<th>A1</th>
<th>W/R</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>0/1</td>
</tr>
</tbody>
</table>

5.3 I²C protocol

The I²C interface protocol has special bus signal conditions. Start (S), stop (P) and binary data conditions are shown below. At start condition, SCL is high and SDA has a falling edge. Then the slave address is sent. After the 7 address bits, the direction control bit R/W selects the read or write operation. When a slave device recognizes that it is being addressed, it should acknowledge by pulling SDA low in the ninth SCL (ACK) cycle.

At stop condition, SCL is also high, but SDA has a rising edge. Data must be held stable at SDA when SCL is high. Data can change value at SDA only when SCL is low.

Even though VDDIO can be powered on before VDD, there is a chance of excessive power consumption (a few mA) if this sequence is used, and the state of the output pins is undefined so that the bus can be locked. Therefore, VDD must be powered before VDDIO unless the limitations above are understood and not critical.

Figure 7: I²C protocol
5.4 Start temperature and pressure measurement

The timing diagrams to start the measurement of the temperature value UT and pressure value UP are shown below. After start condition the master sends the device address write, the register address and the control register data. The BMP180 sends an acknowledgement (ACKS) every 8 data bits when data is received. The master sends a stop condition after the last ACKS.

Figure 8: Timing diagram for starting pressure measurement

Abbreviations:
S Start
P Stop
ACKS Acknowledge by Slave
ACKM Acknowledge by Master
NACKM Not Acknowledge by Master

Table 8: Control registers values for different internal oversampling_setting (oss)

<table>
<thead>
<tr>
<th>Measurement</th>
<th>Control register value (register address 0xF4)</th>
<th>Max. conversion time [ms]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature</td>
<td>0x2E</td>
<td>4.5</td>
</tr>
<tr>
<td>Pressure (oss = 0)</td>
<td>0x34</td>
<td>4.5</td>
</tr>
<tr>
<td>Pressure (oss = 1)</td>
<td>0x74</td>
<td>7.5</td>
</tr>
<tr>
<td>Pressure (oss = 2)</td>
<td>0xB4</td>
<td>13.5</td>
</tr>
<tr>
<td>Pressure (oss = 3)</td>
<td>0xF4</td>
<td>25.5</td>
</tr>
</tbody>
</table>
5.5 Read A/D conversion result or E²PROM data

To read out the temperature data word UT (16 bit), the pressure data word UP (16 to 19 bit) and the E²PROM data proceed as follows:

After the start condition the master sends the module address write command and register address. The register address selects the read register:

E²PROM data registers 0xAA to 0xBF
Temperature or pressure value UT or UP 0xF6 (MSB), 0xF7 (LSB), optionally 0xF8 (XLSB)

Then the master sends a restart condition followed by the module address read that will be acknowledged by the BMP180 (ACKS). The BMP180 sends first the 8 MSB, acknowledged by the master (ACKM), then the 8 LSB. The master sends a ”not acknowledge” (NACKM) and finally a stop condition.

Optionally for ultra high resolution, the XLSB register with address 0xF8 can be read to extend the 16 bit word to up to 19 bits; refer to the application programming interface (API) software rev. 1.1 (”BMP180_API”, available from Bosch Sensortec).

Figure 9: Timing diagram read 16 bit A/D conversion result
6. Package

6.1 Pin configuration

Picture shows the device in top view. Device pins are shown here transparently only for orientation purposes.

![Pin Configuration Diagram]

Figure 10: Layout pin configuration BMP180

Table 9: Pin configuration BMP180

<table>
<thead>
<tr>
<th>in No</th>
<th>Name</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>CSB*</td>
<td>Chip select</td>
</tr>
<tr>
<td>2</td>
<td>VDD</td>
<td>Power supply</td>
</tr>
<tr>
<td>3</td>
<td>VDDIO</td>
<td>Digital power supply</td>
</tr>
<tr>
<td>4</td>
<td>SDO*</td>
<td>SPI output</td>
</tr>
<tr>
<td>5</td>
<td>SCL</td>
<td>I2C serial bus clock input</td>
</tr>
<tr>
<td>6</td>
<td>SDA</td>
<td>I2C serial bus data (or SPI input)</td>
</tr>
<tr>
<td>7</td>
<td>GND</td>
<td>Ground</td>
</tr>
</tbody>
</table>

* A pin compatible product variant with SPI interface is possible upon customer’s request. For I²C (standard case) CSB and SDO are not used, they have to be left open. All pins have to be soldered to the PCB for symmetrical stress input even though they are not connected internally.
6.2 Outline dimensions

The sensor housing is a 7Pin LGA package with metal lid. Its dimensions are 3.60mm (±0.1 mm) x 3.80mm (±0.1 mm) x 0.93mm (±0.07 mm).

Note: All dimensions are in mm.

6.2.1 Bottom view

![Bottom view BMP180](image)

**BOTTOM VIEW**

Figure 11: Bottom view BMP180
6.2.2 Top view

![Top view diagram of BMP180 sensor](image)

Figure 12: Top view BMP180

6.2.3 Side view

![Side view diagram of BMP180 sensor](image)

Figure 13: Side view BMP180
6.3 Moisture sensitivity level and soldering

The BMP180 is classified MSL 1 (moisture sensitivity level) according to IPC/JEDEC standards J-STD-020D and J-STD-033A.

The device can be soldered Pb-free with a peak temperature of 260°C for 20 to 40 sec. The minimum height of the solder after reflow shall be at least 50µm. This is required for good mechanical decoupling between the sensor device and the printed circuit board (PCB).

To ensure good solder-ability, the devices shall be stored at room temperature (20°C).

The soldering process can lead to an offset shift.

6.4 RoHS compliance

The BMP180 sensor meets the requirements of the EC directive "Restriction of hazardous substances (RoHS)", please refer also to:


The BMP180 sensor is also halogen-free.

6.5 Mounting and assembly recommendations

In order to achieve the specified performance for you design, the following recommendations and the “Handling, soldering & mounting instructions BMP180” should be taken into consideration when mounting a pressure sensor on a printed-circuit board (PCB):

- The clearance above the metal lid shall be 0.1mm at minimum.
- For the device housing appropriate venting needs to be provided in case the ambient pressure shall be measured.
- Liquids shall not come into direct contact with the device.
- During operation the sensor is sensitive to light, which can influence the accuracy of the measurement (photo-current of silicon).
- The BMP180 shall not the placed close the fast heating parts. In case of gradients > 3°C/sec. it is recommended to follow Bosch Sensortec application note ANP015, "Correction of errors induced by fast temperature changes". Please contact your Bosch Sensortec representative for details.
7. Legal disclaimer

7.1 Engineering samples

Engineering Samples are marked with an asterisk (*) or (e). Samples may vary from the valid technical specifications of the product series contained in this data sheet. They are therefore not intended or fit for resale to third parties or for use in end products. Their sole purpose is internal client testing. The testing of an engineering sample may in no way replace the testing of a product series. Bosch Sensortec assumes no liability for the use of engineering samples. The Purchaser shall indemnify Bosch Sensortec from all claims arising from the use of engineering samples.

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7.3 Application examples and hints

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8. Document history and modification

<table>
<thead>
<tr>
<th>Rev. No</th>
<th>Chapter</th>
<th>Description of modifications/changes</th>
<th>Date</th>
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<tbody>
<tr>
<td>1.0</td>
<td></td>
<td>First edition for description of serial production material – Preliminary version</td>
<td></td>
</tr>
<tr>
<td>1.1</td>
<td>5.1</td>
<td>New nomenclature of pin configuration</td>
<td>27 July 2010</td>
</tr>
<tr>
<td>1.2</td>
<td>5</td>
<td>Design change in package – hole in Lid and without slit</td>
<td>13 September 2010</td>
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</table>
| 1.3     | 3.2 5.1 | - Standardizing pin naming over Bosch Sensortec products – typical application circuit  
- Optimizing pin description, SPI description | 15 December 2010 |
| 2.0     | 1       | - Non-preliminary version  
- Verifying parameter through characterization | 28 January 2011 |
| 2.1     | 3.2 4 5.3 6.1 6.2.1 | - Declaration of SDO and CSB pins in the typical application circuit  
- Adding global memory map and bits description  
- Power-up sequence  
- Description of used interfaces  
- Dimension pin7 | 1 April 2011 |
| 2.2     | 6.1     | Correction of the pin configuration (editorial change) | 14 April 2011 |
| 2.3     | 3.3     | Optimizing noise performance | 25 May 2011 |
| 2.4     | 6.3     | Removed shelf-life constraints | 26 January 2012 |
|         | page 2  | Comparison removed |      |
|         | 5.1     | Voltage output low level added |      |
|         | 5.3     | Power on sequence of VDD and VDDIO defined |      |
| 2.5     | 1       | Added max values for supply current for restricted version | 15 Feb 2013 |
|         | 1       | Added max value for standby current for restricted version |      |
|         | Figure 4 | Update of calculation of algorithm for pressure and temperature measurement | 5 Apr 2013 |
|         | Page 2  | Changed wording from “ultra high resolution mode” to “advanced resolution mode” |      |